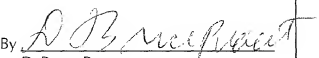


FORM PTO-1390 (REV. 10-97)		U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE	
TRANSMITTAL LETTER TO THE UNITED STATES DESIGNATED/ELECTED OFFICE (DO/EO/US) CONCERNING A FILING UNDER 35 U.S.C. 371		DATE: September 8, 2000	
		EXPRESS MAIL LABEL NO. EL496231891US	
		ATTORNEY DOCKET NO. 40265/DBP/E43	
		U.S. APPLICATION NO. 09/623840	
INTERNATIONAL APPLICATION NO PCT/EP99/01585	INTERNATIONAL FILING DATE 11 March 1999	PRIORITY DATE CLAIMED 11 March 1998	
TITLE OF INVENTION MOTOR VEHICLE ACTUATING DEVICE			
APPLICANT(S) FOR DO/EO/US LOB, Helke			
Applicant herewith submits to the United States Designated/Elected Office (DO/EO/US) the following items and other information:			
<ol style="list-style-type: none">1. <input checked="" type="checkbox"/> This is a FIRST submission of items concerning a filing under 35 U.S.C. 3712. <input type="checkbox"/> This is a SECOND or SUBSEQUENT submission of items concerning a filing under 35 U.S.C. 371.3. <input checked="" type="checkbox"/> This is an express request to begin national examination procedures (35 U.S.C. 371(f)) at any time rather than delay examination until the expiration of the applicable time limit set in 35 U.S.C. 371(b) and PCT Articles 22 and 39(1).4. <input checked="" type="checkbox"/> A proper Demand for International Preliminary Examination was made by the 19th month from the earliest claimed priority date.5. <input checked="" type="checkbox"/> A copy of the International Application as filed (35 U.S.C. 371(c)(2)).<ol style="list-style-type: none">a. <input checked="" type="checkbox"/> is transmitted herewith (required only if not transmitted by the International Bureau).b. <input checked="" type="checkbox"/> has been transmitted by the International Bureau.c. <input type="checkbox"/> is not required, as the application was filed in the United States Receiving Office (RO/LUS).6. <input type="checkbox"/> A translation of the International Application into English (35 U.S.C. 371(c)(2)).7. <input type="checkbox"/> Amendments to the claims of the International Application under PCT Article 19 (35 U.S.C. 371(c)(3)).<ol style="list-style-type: none">a. <input type="checkbox"/> are transmitted herewith (required only if not transmitted by the International Bureau).b. <input type="checkbox"/> have been transmitted by the International Bureau.c. <input type="checkbox"/> have not been made; however, the time limit for making such amendments has NOT expired.d. <input type="checkbox"/> have not been made and will not be made.8. <input type="checkbox"/> A translation of the amendments to the claims under PCT Article 19 (35 U.S.C. 371(c)(3)).9. <input checked="" type="checkbox"/> An oath or declaration of the inventor(s) (35 U.S.C. 371(c)(4)). (unexecuted)10. <input type="checkbox"/> A translation of the annexes to the International Preliminary Examination Report under PCT Article 36 (35 U.S.C. 371(c)(5)).			
Items below concern other document(s) or other information included:			
<ol style="list-style-type: none">11. <input checked="" type="checkbox"/> An Information Disclosure Statement under 37 CFR 1.97 and 1.98.12. <input type="checkbox"/> An assignment document for recording. A separate cover sheet in compliance with 37 CFR 3.28 and 3.31 is included.13. <input type="checkbox"/> A FIRST preliminary amendment. <input type="checkbox"/> A SECOND or SUBSEQUENT preliminary amendment.14. <input type="checkbox"/> A substitute specification.15. <input type="checkbox"/> A change of power of attorney and/or address letter.16. <input type="checkbox"/> Small entity claim with a copy of this transmittal letter attached.17. <input checked="" type="checkbox"/> International search report.18. <input checked="" type="checkbox"/> International preliminary examination report.19. <input checked="" type="checkbox"/> Extra set of drawings20. <input type="checkbox"/>21. <input type="checkbox"/>			

533 Rec'd PCT/PTO 08 SEP 2000

U.S. APPLICATION NO. (if known, see 37 CFR 1.5) N/A 09/623840		INTERNATIONAL APPLICATION NO. PCT/EP99/01585		ATTORNEY DOCKET NO. 40265/DBP	
<input checked="" type="checkbox"/> The following fees are submitted: (see Note (1) below) Basic National Fee (37 CFR 1.492(a)(1-5)): Search Report has been prepared by the EPO or JPO \$ 840.00 International preliminary examination fee paid to USPTO (37 CFR 1.482) ... \$ 670.00 No international preliminary examination fee paid to USPTO (37 CFR 1.482) but international search fee paid to USPTO (37 CFR 1.445(a)(2)) \$ 690.00 Neither international preliminary examination fee (37 CFR 1.482) nor international search fee (37 CFR 1.445(a)(2)) paid to USPTO \$ 970.00 International preliminary examination fee paid to USPTO (37 CFR 1.482) and all claims satisfied provisions of PCT Article 33(2)(4) \$ 96.00 ENTER APPROPRIATE BASIC FEE AMOUNT = \$ 840				CALCULATIONS PTO USE ONLY	
Surcharge of \$130 for furnishing the oath or declaration later than <input type="checkbox"/> 20 <input checked="" type="checkbox"/> 30 months from the earliest claimed priority date (37 CFR 1.492(e)).				\$ 130	
Claims	Number Filed	Number Extra	Rate		
Total Claims	22 -20=	2	X \$18	\$ 36	
Independent Claims	1 -3=	0	X \$78	\$ 0	
Multiple dependent claim(s) (if applicable)			+ \$260	\$ 0	
TOTAL OF ABOVE CALCULATIONS =				\$ 1006	
Reduction by 1/2 for filing by small entity, if applicable. Verified Small entity statement must also be filed. (Note 37 CFR 1.9, 1.27, 1.28).					
SUBTOTAL =				\$ 1006	
Processing fee of \$130 for furnishing the English translation later than <input type="checkbox"/> 20 <input checked="" type="checkbox"/> 30 months from the earliest claimed priority date (37 CFR 1.492(f)).				\$ 130	
TOTAL NATIONAL FEE =				\$ 1136	
Fee for recording the enclosed assignment (37 CFR 1.21(h)). The assignment must be accompanied by an appropriate cover sheet (37 CFR 3.28, 3.31). \$40.00 per property				\$	
TOTAL FEES ENCLOSED =				\$ 1136	
Note (1): The basic national fee must be paid when filing this application. The 20-month time limit (37 CFR § 1.494) and 30-month time limit (37 CFR § 1.495) are not extendable.				Amount to be refunded \$ charged \$	
a. <input checked="" type="checkbox"/> A check in the amount of \$ 1136 to cover the above fees is enclosed. b. <input type="checkbox"/> Please charge my Deposit Account No. _____ in the amount of \$ _____ to cover the above fees. A duplicate copy of this sheet is enclosed. c. <input checked="" type="checkbox"/> The Commissioner is hereby authorized to charge any additional fees which may be required, or credit any overpayment to Deposit Account No. 03-1728 . A duplicate copy of this sheet is enclosed.					
NOTE (2): Where an appropriate time limit under 37 CFR 1.494 or 1.495 has not been met, a petition to revive (37 CFR 1.137(a) or (b)) must be filed and granted to restore the application to pending status.					
SEND ALL CORRESPONDENCE TO: D. Bruce Prout CHRISTIE, PARKER & HALE P.O. Box 7068 Pasadena, CA 91109-7068					
				By  D. Bruce Prout Reg. No. 20,958	

Docket No. : 40265/DBP/E43

Applicant or Patentee : Helke Lob

Application or Patent No. : 09/623,840

Filed or Issued : September 8, 2000

Entitled : MOTOR VEHICLE ACTUATING DEVICE



CHRISTIE, PARKER & HALE, LLP
Post Office Box 7068
Pasadena, CA 91109-7068
(626) 795-9900

**VERIFIED STATEMENT (DECLARATION) CLAIMING SMALL ENTITY STATUS
(37) CFR 1.9(f) & 1.27(c) - SMALL BUSINESS CONCERN**

I hereby declare that I am

X the owner of the small business concern identified below:

_____ an official of the small business concern empowered to act on behalf of the concern identified below:

NAME OF SMALL BUSINESS CONCERN : MEDIZINISCHE INNOVATIONEN

ADDRESS OF SMALL BUSINESS CONCERN : Eltwerder Strasse 82, D-81377 Munich, Germany

I hereby declare that the above identified small business concern qualifies as a small business concern as defined in 13 CFR 121.12, and reproduced in 37 CFR 1.9(d), for the purposes of paying reduced fees to the United States Patent and Trademark Office, in that the number of employees of the concern, including those of its affiliates, does not exceed 500 persons. For purposes of this statement, (1) the number of employees of the business concern is the average over the previous fiscal year of the concern of the persons employed on a full-time, part-time or temporary basis during each of the pay periods of the fiscal year, and (2) concerns are affiliates of each other when either, directly or indirectly, one concern controls or has the power to control the other, or a third party or parties controls or has the power to control both.

I hereby declare that rights under contract or law have been conveyed to and remain with the small business concern identified above with regard to the invention entitled **MOTOR VEHICLE ACTUATING DEVICE** by inventor(s) **Helke Lob** described in

_____ the specification filed herewith

X Application No. 09/623,840 filed September 8, 2000

_____ Patent No. _____ issued _____

If the rights held by the above identified small business concern are not exclusive, each individual, concern or organization having rights in the invention is listed below" and no rights to the invention are held by any person, other than the inventor, who would not qualify as an independent inventor under 37 CFR 1.9(c) if that person made the invention, or by any concern which would not qualify as a small business concern under 37 CFR 1.9(d), or a nonprofit organization under 37 CFR 1.9(e). *NOTE: Separate verified statements are required from each named person, concern or organization having rights to the invention averring to their status as small entities. (37 CFR 1.27)

NAME :

ADDRESS :

INDIVIDUAL SMALL BUSINESS CONCERN NONPROFIT ORGANIZATION

VERIFIED STATEMENT (DECLARATION) CLAIMING SMALL ENTITY STATUS
(37) CFR 1.9(f) & 1.27(c) - SMALL BUSINESS CONCERN

Docket No.: 40265/DBP/E43

NAME :
ADDRESS :

☐ INDIVIDUAL ☐ SMALL BUSINESS CONCERN ☐ NONPROFIT ORGANIZATION

I acknowledge the duty to file, in this application or patent, notification of any change in status resulting in loss of entitlement to small entity status prior to paying, or at the time of paying, the earliest of the issue fee or any maintenance fee due after the date on which status as a small entity is no longer appropriate. (37 CFR 1.28(b))

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under section 1001 of Title 18 of the United States Code, and that such willful false statements may jeopardize the validity of the application, any patent issuing thereon, or any patent to which this verified statement is directed.

NAME OF PERSON SIGNING :
TITLE OF PERSON IF OTHER THAN OWNER :
ADDRESS OF PERSON SIGNING :

SIGNATURE

Helle Sol

DATE

4. Oktober 2000

DBP/aam

AAM PAS271812 1--9/6/00 6:28 PM

IN THE UNITED STATES PATENT AND TRADE MARK OFFICE

VERIFICATION OF TRANSLATION

I, Michael Wallace Richard Turner, Bachelor of Arts, Chartered Patent Attorney, European Patent Attorney, of 1 Horsefair Mews, Romsey, Hampshire SO51 8JG, England, do hereby declare that I am conversant with the English and German languages and that I am a competent translator thereof;

I verify that the attached English translation is a true and correct translation made by me of the attached specification in the German language of International Application PCT/EP99/01585;

I further declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment or both under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Date: September 8, 2000

MWR Turner

M W R Turner

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant : Helke Lob
Application No. : 09/623,840
Filed : September 8, 2000
Title : MOTOR VEHICLE ACTUATING DEVICE
Grp./Div. : N/A
Examiner : N/A
Docket No. : 40265/DBP/E43

PRELIMINARY AMENDMENT

Assistant Commissioner for Patents
Washington, D.C. 20231

Post Office Box 7068
Pasadena, CA 91109-7068
September 28, 2001

Commissioner:

Please amend the above-identified application as follows:

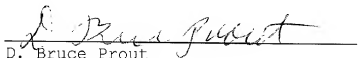
-- CROSS-REFERENCE TO RELATED APPLICATION

This application claims priority of International application No. PCT/EP99/01585, which in turn claims priority to German patent application number 198 11 268.8, filed 11 March 1998. --

Respectfully submitted,

CHRISTIE, PARKER & HALE, LLP

By


D. Bruce Prout
Reg. No. 20,958
626/795-9900

DBP/djp

DJP PAS383978.1--9/28/01 3:59 PM

Express Mail No.

EL3887904US

Berlin 11th March 1999
Our ref: MB8032 HC/oe
Applicants/proprietors: Medizinische Innovationen
Office ref: New application

Medizinische Innovationen
Ehrwalder Strasse 82, D-81377 Munich

Actuating apparatus for a motor vehicle

The invention concerns an actuating apparatus for operating the drive, steering or retardation means of a motor vehicle, as set forth in the classifying portion of claim 1.

5 Known actuating apparatuses of that kind are generally in the form of a foot pedal which transmits the pedal pressure to the element to be activated by way of a lever transmission assembly and a cable or a hydraulic line.

10 A disadvantage of the known pedals is that the pedals and the connected linkages which are joined thereto entail a serious risk of injury in the event of an accident involving deformation of the passenger cell. For structural reasons it is also not possible for that risk of injury to be reduced by crumble zones or other deformation regions as the amount of space available for same is limited.

Therefore the object of the invention is to develop a foot-actuated actuating apparatus for a motor vehicle, which by virtue of its structural configuration in the event of a frontal impact of the motor vehicle substantially eliminates foot injuries to the vehicle driver.

5 That object is attained by the features recited in characterizing portion of claim 1.

The invention embraces the technical teaching that, for the purposes of actuating drive or retardation or deceleration means in a motor vehicle, there is provided a signal converter which has an elastic and conductive shaped body, wherein the shaped body has two electrical contact regions which are disposed on mutually opposite surfaces of the shaped body and which each have a respective feed line, and the feed lines are taken into a measurement transducer, at the output of which is a control signal as a measurement for the electrical resistance.

15 This therefore provides an actuating means which in normal operation, upon compression by means of a foot pressure, reduces its resistance and outputs a control signal, as was hitherto produced by actuating the accelerator pedal, the brake pedal or the clutch pedal. In corresponding aircraft, the side rudder is correspondingly actuated. In the event of a collision, the compression effect serves to absorb the thrust force acting on the feet of the operator in the event of deformation of the vehicle, and in that way reduces the risk of injury.

In a preferred embodiment of the invention the shaped body comprises an elastic material. Advantageously, the elastic material is porous, in which case the pores may certainly be of an irregular arrangement. In that respect, in regard to the frequency distribution of the size of the pores, a variance which is not zero is to be provided. In a desirable variant the shaped body comprises an elastomer.

25 Preferably the shaped body comprises two shaped body portions which are arranged conductively one above the other. Each of the shaped body portions on the surface remote from the respective other shaped

body portion, is completely provided with a respective electrical contact region. The respective contact region is conductively connected on the one hand to the corresponding shaped body and on the other hand to a respective feed line.

- 5 Advantageously, the moduli of elasticity of the materials forming the shaped body portions are of different magnitudes, wherein the shaped body portions, along a connecting line between the two contact regions, are of different extents in such a way that a spacing, referred to as the pressure point, of the two contact regions occurs, at which only one of the
- 10 two shaped body portions is substantially completely compressed.

- In an advantageous embodiment the shaped body which is provided with the corresponding contact regions and feed lines is enclosed by an insulating material. In this arrangement, the material is to be provided in such a way that the surfaces covering the respective contact regions are
- 15 stiffened so that a pressure locally exerted in the stiffened region is applied to the shaped body in substantially uniformly distributed fashion over the stiffened region. The material encasing the other regions of the shaped body is of a yielding nature.

- In accordance with an advantageous development of the invention
- 20 the signal converter of any actuating apparatus has a shaped body comprising a cellular polyurethane or cellular vulkollan, whose electrical resistance decreases upon volume compression. That material absorbs substantial energy with progressive deformation thereof so that thrust or shock energy acting on the feet of the operator is reduced.

- 25 The cell structure of the shaped body comprising an elastomer is formed by homogenous superimposition of two structure elements. The shaped body is porous, with the pores being arranged in irregularly distributed manner. For that purpose, incorporated in the pores of the elastomer are balls, preferably hollow balls, which themselves are
- 30 compressible and electrically conductive. That advantageously provides

that a reduction in the electrical resistance is achieved by a relatively large number of contact locations within the compressed shaped body.

Mounted to the shaped body is a first contact region which extends over the entire surface towards the driver, and which is conductively
5 connected to the shaped body. The contact region is further provided with a feed line which is taken outwardly from the signal converter through the shaped body. A second contact region of the shaped body, which is arranged in opposite relationship to the first contact region, is conductively connected to a feed line. The shaped body is enclosed by an
10 insulating material in the manner of a housing, wherein the material is stiff in the region of the wall regions of the housing, which cover the contact regions, while in the other wall regions the material is pliable. That thus means that a pressure locally applied in the stiffened region is applied to the shaped body in such a fashion as to be substantially uniformly
15 distributed over the stiffened region.

The invention affords the advantageous option of so designing a novel actuating element which can advantageously be integrated into the electronic signal processing system of present-day motor vehicle technology, that in the event of an accident it forms a safety element.

20 By virtue of the additional inclusion of elastic elements in the form of balls in the pores of the elastomer, preferably cellular polyurethane or cellular vulkollan, the shaped body can have a compression characteristic of a desirable configuration. That configuration of the compression characteristic of the shaped body which for example forms a compressibly
25 shock-absorbing foot well lining in a motor vehicle with a maximum level of energy absorption in the final deformation region has in particular an initial region where the shaped body can be deformed in a finely controllable manner and there is a substantially linear relationship between the absorbed energy E and the compression stroke distance S .

30 If the elastomer body is porous or if the inclusions are in the form of conductive hollow bodies, the range of variation in the electrical

resistance which alters when the body is compressed is increased. The pores or cavities thus form contact surfaces which increasingly come into contact with each other when compression occurs, and thus markedly reduce the electrical resistance of the overall arrangement, because of the distances to be traversed by the electric current being reduced.

As the shock-absorbing foot well lining is designed for maximum energy absorption in the final deformation region, in contrast with a substantial compression stroke distance S there is a functional relationship such that the mechanical energy E which is absorbed upon compression by the foot well lining rises in an over-proportional fashion. In the region of considerable compression, the compression characteristic is of a substantially quadratic or exponential characteristic configuration.

In an advantageous embodiment the signal converter of the design configuration as described hereinbefore is grooved in the region of a first contact region or is provided in some other fashion with a surface coating which increases the coefficient of friction so that the foot enjoys non-slip contact therewith.

Preferably, arranged downstream of the signal converter is a measurement transducer whose inputs are connected by way of the feed lines to the first and a second contact region. The measurement transducer includes a voltage source which applies a substantially constant electrical voltage between the first and the second contact regions. In an advantageous embodiment there is provided a current source which produces an electrical current of substantially constant amplitude between the first and the second electrical contact regions. There is preferably provided a transducer which at the input side is connected to the feed lines and at the output of which there is produced an analog electrical parameter. The analog electrical parameter is advantageously applied to an input amplifier which boosts the amplitude of the analog electrical parameter as a measurement in respect of the electrical resistance. In an advantageous variant the measurement transducer has an analog-digital

converter which receives the analog parameter as an input signal and outputs it in the form of a digital parameter.

Preferably there is provided a function generator to which the analog or digital parameter is applied and at the output of which there is a control signal which is in an unequivocal relationship with the parameter or the variation in time thereof. In an advantageous variant the function generator has a memory to which the analog or digital parameter is fed. The arrangement also has a differentiation stage which receives the current parameter and a previous parameter called up from the memory as input signals and which outputs a differentiation value which represents a measurement in respect of the variation in time of the parameter. Advantageously the function generator has a linearization member to which the parameter or the differentiation value is applied as an input signal and at the output of which occurs the control signal. Ultimately the control signal activates the drive or retardation means.

In an advantageous embodiment, to control the drive or retardation means in dependence on a predetermined parameter, there is provided a first threshold stage which receives the parameter as an input signal and which outputs a control signal which is of a first characteristic value when the parameter is greater than or equal to a predetermined parameter threshold or a second characteristic value when the parameter is smaller than the predetermined parameter threshold. In a further advantageous variant the function generator, for controlling the drive or retardation means in dependence on a predetermined differentiation value, has a second threshold stage which receives the differentiation value as an input signal and which outputs a control signal which is of a constant first differentiation magnitude when the differentiation value is greater than or equal to a predetermined differentiation value threshold and which is of a second differentiation magnitude when the differentiation value is less than the predetermined differentiation value threshold.

Advantageously the function generator also has a table store or memory in which there is associated with each digital value of the parameter and/or of the differentiation value a corresponding value of the control signal.

5 In an advantageous embodiment the measurement transducer further includes an output stage which receives the control signal and increases it in terms of its amplitude.

Preferably, there is provided an apparatus which detects the derivative of the change in the electrical resistance determined by the
10 control signal and which in the event of a fast change in the electrical resistance increases the acceleration of the vehicle so that a kick-down effect is produced.

An advantageous variant provides three actuating apparatuses, wherein a first actuating apparatus influences the vehicle engine, a second
15 actuating apparatus influences the braking system and a third actuating apparatus influences the clutch. In that case, the signal converters of the actuating apparatuses are preferably integrated into an overall shaped body, wherein the actuating surfaces of the actuating apparatuses are arranged in mutually juxtaposed relationship in a surface of the overall
20 shaped body in such a way that the actuating surface of the first actuating apparatus is to the right, that of the second actuating apparatus is in the center and that of the third actuating apparatus is to the left. In an advantageous embodiment the actuating surface of the second actuating apparatus is substantially larger than the actuating surfaces of the other
25 apparatuses. Furthermore, the spacing between the actuating surfaces of the second and third actuating apparatuses is to be larger than that between the actuating surfaces of the first and second actuating apparatuses. The actuating group formed from the three actuating apparatuses is installed on the driving side in the front wall defining the
30 foot well in the direction of travel, in such a way that the three actuating surfaces face towards the driver.

In another embodiment of the invention the shaped body comprises a closed housing which is variable in volume and which is let into the front wall. In that arrangement the actuating apparatus has a pressure-receiving member of a mat-like configuration, which is fixed to the housing in such a way as to be accessible to the driver from the foot well of the passenger cell of the motor vehicle. The housing is of a two-part structure and is preferably of a cuboidal configuration. It has a cup-shaped bottom portion and a cover of the same shape. The walls of the bottom portion and of the cover which engages over the bottom portion are connected together in the form of a guide means and are arranged displaceably relative to each other. In that arrangement the housing portions are of a stiff nature.

Provided in the interior of the housing are a plurality of spring elements by way of which the housing cover which carries the pressure-receiving member is supported on the bottom and which urge the housing cover into its initial position after a pressure loading has been applied. Due to the action of the spring elements, the impression of the existence of a conventional pedal construction is also generated in the person actuating the actuating apparatus, in a psychologically desirable fashion, although the force loading the actuating apparatus does not act directly on the drive or retardation means of the motor vehicle but is converted into a preferably electrical control signal which in turn activates the drive or retardation means.

In accordance with an advantageous development of the invention the spring elements are in the form of straight coil springs with a non-linear characteristic whereby the counteracting pressure of the spring elements increases in the event of a heavy pressure loading on the pressure-receiving member, that is to say upon a relatively great reduction in the volume of the housing, and increases the impression of the existence of a conventional pedal arrangement for actuation of the drive or retardation means of a motor vehicle.

In accordance with another development of the above-described embodiment of the invention, the pressure-receiving member in the form of a receiving surface is of a structural configuration such that as a structural unit it represents an electrical resistance which is variable in dependence on pressure, an inductance or a capacitance which is variable by pressure-dependent deformation. The change in the corresponding resistance, capacitance and inductance values results in changes in voltage for example due to a variation in the equilibrium of a resistance bridge or upon detuning of a resonant circuit, which changes in voltage after amplification can be used as a control voltage for activation of the engine, the brake or the clutch of the motor vehicle.

It is equally also possible to use a pressure-receiving member which is in the form of a hydraulic system and in which different control voltages are activated by means of a hydraulic medium in dependence on pressure by way of contact means.

Advantageous developments of the invention are characterized in the appendant claims or are set forth in greater detail hereinafter together with the description of the preferred embodiment of the invention. In the drawings:

Figure 1 is a perspective view of an actuating group with three actuating apparatuses for controlling a braking or clutch arrangement, wherein the respective actuating apparatus has a variable-volume housing with a pressure-receiving member mounted thereon,

Figure 2 is a view in section taken along line A...A in Figure 1,

Figure 3 shows a block circuit diagram for the control of a braking or clutch arrangement of a motor vehicle by means of an actuating apparatus as shown in Figure 1,

Figure 4 is a perspective view of an actuating group with three actuating apparatuses for controlling a drive or retardation means, wherein the respective actuating apparatus has a shaped body comprising an elastic material, in accordance with the preferred embodiment,

Figure 5 is a view in section taken along line B...B in Figure 4,
Figure 6 shows a block circuit diagram of an actuating apparatus as shown in Figure 4,

Figure 7 shows an advantageous development of the invention as a section taken along line B...B in Figure 4, and

Figure 8 shows a compression characteristic of the development of the invention as shown in Figure 7.

Shown in the portion, as illustrated in a perspective view in Figure 1, of a front wall 4 disposed between the engine compartment and the passenger compartment of a motor vehicle, is the position of an actuating apparatus 1, 1' according to the invention for the braking arrangement or clutch arrangement (not shown) of a motor vehicle. The actuating apparatuses 1, 1' each have a cuboidal housing 2, 2', while a pressure-receiving member 3, 3' is secured to the wall portion of the housing 2, 2', which projects into the foot region of the passenger compartment and which extends in a plane parallel to the wall 4.

The respective pressure-receiving member 3, 3', as part of an electrical or pneumatic converter system, is capable when a pressure loading is applied thereto of triggering an electrical control voltage which activates the braking or clutch arrangement of the motor vehicle. The housing 2, 2' of the respective actuating apparatus 1, 1', which carries the pressure-receiving member 3, 3' which is of a mat-like nature is arranged displaceably perpendicularly to the plane defined by the wall 4 and is completely recessed into the wall 4 when a maximum pressure force is applied to the pressure-receiving member 3, 3' or the latter is loaded by feet or legs of the vehicle driver in the event of the motor vehicle being involved in a frontal impact. Such a configuration and arrangement of an actuating apparatus 1, 1' advantageously substantially eliminates the risk of injury caused by the actuating apparatus to the feet of the vehicle driver in the event of the vehicle being involved in a frontal impact. In addition to the actuating apparatuses 1, 1', the drawing also

diagrammatically illustrates an actuating apparatus 5 for actuation of the vehicle engine.

In Figure 2 the actuating apparatus 1 is shown as a diagrammatic view in section taken along line A...A in Figure 1. The housing 2 of the actuating apparatus 1 is fixed in position by means of a holder provided at the side of the wall 4, which is towards the engine compartment. The cuboidal housing 2 which is of a two-part nature has a cup-shaped bottom portion 7 and a cover 6 which is also of a cup-shaped configuration and which engages over the bottom portion 7. The bottom portion 7 and the cover 6 are connected together by a rectilinear guide 9.

On its front the housing cover 6 carries the pressure-receiving member 3 which is of a mat-like nature. Arranged in the interior of the housing 2 in a symmetrical configuration are three spring elements 8 on which the cover 6 is supported against the housing bottom portion 7 when the pressure-receiving member 3 is loaded in the appropriate fashion. The spring elements are in the form of straight coil springs and return the housing cover 6 back to its starting position when the actuating apparatus 1 is no longer subjected to a pressure loading. A non-linear characteristic of the spring elements 8 advantageously produces a counteracting pressure which is sufficiently great for the pressure loading, and at the same time upon operation by the vehicle driver they provide an operating characteristic in respect of the actuating apparatus 1 according to the invention, which substantially corresponds to an actuating apparatus which is fitted with pedals.

Displaceability of the housing cover 6, which is ensured by the spring elements 8 and the guide means 9, in the event of the vehicle being involved in a frontal impact, makes it possible for the parts of the actuating apparatus 1, which project into the foot well of the passenger compartment cell, to be completely lowered into the plane defined by the wall 4. That advantageously almost completely eliminates the risk of foot injury, arising out of the presence of the actuating apparatus. The signal

lines 3.1 and 3.2 of the pressure-receiving member 3 are taken through the bottom portion 7 of the housing into the engine compartment and connected to a system 20 in which the transducers and amplifiers necessary to produce the required control voltage and the motor vehicle
5 braking or clutch arrangement to be activated are combined.

The electrical block circuit diagram shown in Figure 3 for the control of a braking or clutch arrangement of a motor vehicle by means of an actuating apparatus according to the invention shows the structure of the system 20 in greater detail. In this case the mat-type pressure-receiving
10 member 3 is of a variable-pressure nature and is acted upon by a surface load P. The signal lines 3.1 and 3.2 make a connection to an electrical resonant circuit 11 whose resonance frequency is varied by the parallel connection of the pressure-receiving member and the different loading thereon. The resulting voltage fluctuation is adapted in an amplifier 12 to
15 the required input level of a servo or adjusting member 13 for activating the braking or clutch arrangement 14 of the vehicle.

Figure 4 shows an actuating group comprising three actuating apparatuses 21, 22 and 23, as a perspective view of the preferred embodiment. In this case the actuating apparatuses 21, 22, 23 are each
20 shown in the form of their respective signal converter. The first actuating apparatus 21 serves to actuate a vehicle engine, the second actuating apparatus 22 serves to actuate a braking system and the third actuating apparatus 23 serve to actuate a clutch. In this case the actuating apparatuses 21, 22, 23 are the same in terms of their structural
25 configuration, with the second actuating apparatus 22 being markedly larger than the others. In addition the spacing between the second actuating apparatus 22 and the third actuating apparatus 23 is greater than the spacing between the first actuating apparatus 21 and the second actuating apparatus 22. The signal converters of the three actuating
30 apparatuses 21, 22, 23 are integrated into an overall shaped body 24, with the actuating surfaces 25 of the actuating apparatuses being

disposed in one surface. In this case the overall shaped body 24 has in parallel relationship with the actuating surfaces three rear openings which are not visible in Figure 4 and through which the feed lines extending from the signal converters are taken outwardly through the overall shaped body 24. In a manner which is not shown in the drawing, the shaped body 24 is fitted at the driving side into the wall delimiting the foot well in the direction of travel, in such a way that the three actuating surfaces 25 face towards the driver.

The signal converter 26, which is shown in detail in Figure 5, of any actuating apparatus 21, 22, 23 has a shaped body which is composed of two shaped body portions 27, 28. The shaped body portions 27, 28 each comprise an elastic material and are porous, with the pores being irregularly arranged. In the illustrated view the pores of the shaped body portion 27 which is towards the driver are larger than those of the shaped body portion 28. At the same time the modulus of elasticity of the material forming the shaped body portion 27 is greater than that of the material of the shaped body portion 28 so that, when a surface force P is applied perpendicularly to the surface of the shaped body portion 27 which is towards the driver, essentially only the latter is compressed. Disposed on the shaped body portion 27 is a first contact region 29 which extends over the entire surface area which faces towards the driver, and is conductively connected to the shaped body portion 27. The contact region 29 is further provided with a feed line 30 which is taken outwardly from the signal converter 26 through the shaped body portions 27 and 28. A second contact region 29' is disposed on the surface of the shaped body portion 28, which is remote from the shaped body portion 27, and in the same way as the first contact region 29 is conductively connected to the shaped body portion 28 and a feed line 30'. The shaped body which is composed of the shaped body portions 27 and 28 is enclosed by an insulating material in the manner of a housing, in which case the material in the region of the surfaces 31, 31' covering the contact regions 29, 29' is

stiff while it is pliable in the other surfaces. In the region 31' the insulating material is provided with an opening for the feed lines 30, 30' to be taken out.

Disposed downstream of the signal converter 26 is a measurement transducer 32 which has a plurality of devices and whose inputs, as shown in the block circuit diagram of figure 6, are connected by way of the feed lines 30, 30' to the two contact regions 29, 29' of the signal converter 26. The measurement transducer 32 includes a voltage source 33 which applies a substantially constant electrical voltage between the first contact region 29 and the second contact region 29'. The arrangement also includes a transducer 34 which is connected at its input side to the feed lines 30, 30' and at the output of which an analog electrical parameter 35 is outputted. The parameter 35 is fed to an input amplifier 36 which boosts the parameter 35 in respect of its amplitude. A downstream-connected analog/digital converter 37 receives the analog parameter 35 as an input signal and outputs same in digitized form. The digitized parameter 35' is fed to a function generator 38, the function generator 38 including a plurality of devices. Provided among such devices is a memory 39 to which the parameter 35' is fed. The function generator 38 has a differentiation stage 40 which receives the parameter 35' and a previous parameter 41 outputted by the memory 39, and outputs a differentiation value 42 as a measurement in respect of the variation in time of the parameter 35. Connected downstream of the differentiation stage 40 is a linearization member 43 to which the differentiation value 42 is fed and which outputs a first control signal 44, wherein the first control signal 44 is in a linear relationship with the spacing or the variation in the spacing between the two contact regions 29, 29'.

The measurement transducer 32 further includes an output stage 45 which boosts the first control signal 44 in respect of its amplitude. The control signal 44 activates a drive or retardation means 46.

To control the drive or retardation means 46 in dependence on a predetermined parameter, there is first threshold stage 47 which, upon previous actuation of a switch 48, outputs a second control signal 44' which is fed instead of the first control signal 44 to the drive or retardation means 46 by way of the output stage 45. A predetermined parameter threshold value 49 is previously transferred to the first threshold stage 47. The threshold stage 47 receives the digital parameter 35' as an input signal and outputs the second control signal 44' which is of a first characteristic value when the digital parameter 35' is greater than or equal to the parameter threshold value 49 and which is of a second characteristic value when the parameter 35' is less than the parameter threshold value 49.

To control the drive or retardation means 46 in dependence on a predetermined differentiation value, there is provided a second threshold stage 50 to which a predetermined differentiation value threshold 51 is fed, wherein the second threshold stage 50 outputs a third control signal 40'' upon previous actuation of a switch 52. The third control signal is applied to the input of the drive or retardation means 46, in a manner corresponding to the first control signal 40 and the second control signal 40'.

The function generator 38 also has a table memory or store 53 to which the digital parameter 35' and/or the differentiation value 42 and the control signal 44 are fed, wherein in the table memory 53 there is associated with each value of the respective parameter 35' and/or the differentiation value 42 a corresponding control signal 44.

The signal converter 60 which is shown in detail in Figure 7 of any actuating apparatus (see references 21, 22 and 23 in Figure 4) has a shaped body 61 comprising a cellular polyurethane or cellular vulkollan, the electrical resistance of which is reduced upon a compression in respect of its volume.

The shaped body 61 is porous, with the pores 62 being irregularly arranged. Disposed on the shaped body 61 is a first contact region 63 which extends over the entire surface that faces towards the driver, and is conductively connected to the shaped body 61. The contact region 63 is further provided with a feed line 64 which is taken outwardly from the signal converter 60 through the shaped body 61. A second contact region 65 of the shaped body 61, which is arranged opposite the first one, is conductively connected to a feed line 66. The shaped body 61 is enclosed by an insulating material in the manner of a housing, wherein the material in the region of the wall regions 67 and 68 of the housing, which cover the contact regions 63 and 65, is stiff, while it is flexible and yielding in the other wall regions of the housing. In that way a pressure exerted locally in the stiffened region 68 can be applied to the shaped body 61 in such a way as to be distributed substantially uniformly over the stiffened region.

Provided in the contact region 65 and in the stiff wall region 67 is an opening 69 to take out the lines 64 and 66 which are to be connected to a measurement transducer (see reference 32 in Figure 6).

The cell structure of the shaped body 61 comprising an elastomer is formed by mutual superimposition of two structure elements. For that purpose, incorporated in the pores 62 of the elastomer are balls 70, preferably hollow balls, which are themselves compressible and electrically conductive.

By virtue of the inclusion of elastic elements in ball form in the pores of the elastomer, preferably cellular polyurethane or cellular vulkollan, the shaped body 61 has a special compression characteristic 80 which is shown in diagrammatic form in Figure 8.

The curve configuration of the compression characteristic 80 of the shaped body (see reference 61 in Figure 7) which for example forms a compressibly shock-absorbing foot well lining in a motor vehicle with maximum energy absorption in the final deformation region has an initial region 81 where the shaped body can be deformed in a finely controllable

manner and there is substantially linear relationship between absorbed energy E and compression stroke distance S.

As the shock-absorbing foot well lining is designed for maximum energy absorption in the final deformation region 82, there is in contrast in
5 the case of a large compression stroke distance S a functional relationship such that the mechanical energy E absorbed upon compression increases in over-proportional fashion.

In the region of severe compression 82 the compression characteristic 80 has a substantially quadratic or exponential
10 configuration.

The invention is not limited in terms of implementation thereof to the preferred embodiment set forth hereinbefore. On the contrary a large number of alternative configurations are possible, which make use of the illustrated structure even in configurations of a basically different kind.

CLAIMS

1. An actuating apparatus for operating a drive, steering or retardation means of a motor vehicle, comprising a signal converter (26; 60) which produces a control signal dependent on the actuating travel, characterized in that the signal converter (26; 60) comprises an elastic and conductive shaped body having a first and a second outside surface which are arranged at a spacing relative to each other, which is provided with a first electrical contact region (29; 62) which extends over the first outside surface of the shaped body and which is galvanically conductively connected on the one hand to the shaped body and on the other hand to a first feed line (30; 64) and a second electrical contact region (29'; 63) which extends along the second surface of the shaped body and is galvanically conductively connected on the one hand to the shaped body and on the other hand to a second feed line (30'; 65), wherein the electrical resistance of the shaped body between the two contact regions (29, 29'; 62, 63) is dependent on the spacing of the two contact regions (29, 29'; 62, 63) and that connected downstream of the signal converter (26; 60) is a measurement transducer (32) whose inputs are connected by way of the feed lines (30, 30'; 64, 65) to the first and second contact regions (29, 29'; 62, 63) and at whose output a control signal (44) can be taken off, which is dependent on the electrical resistance of the shaped body.

2. An actuating apparatus as set forth in claim 1 characterized in that the measurement transducer (32) has a voltage source (33) which applies a substantially constant electrical voltage between the first and second contact regions (29, 29'), or that the measurement transducer (32) includes a current source which produces a substantially constant current between the first and second electrical contact regions (29, 29').

3. An actuating apparatus as set forth in claim 1 characterized in that the measurement transducer (32) includes an input amplifier (36) which is connected (30; 30') at the input side to the feed lines.

4. An actuating apparatus as set forth in claim 1 characterized in that the measurement transducer (32) has an analog/digital converter (37) which receives the analog parameter (35) as an input signal and digitizes it.

5. An actuating apparatus as set forth in claim 1 characterized in that the measurement transducer (32) has a function generator (38) which receives the analog (35) or the digital parameter (35') as an input signal and at whose output the control signal (44) which is in an unequivocal functional relationship with the parameter (35, 35') can be taken off.

6. An actuating apparatus as set forth in claim 5 characterized in that the function generator (38) has a differentiation stage (40) which receives the current parameter (35, 35') and the previous parameter (42) called up from the memory (49) as input signals and outputs at its output a differentiation value (42) which represents a measurement in respect of the variation in time of the parameter (35).

7. An actuating apparatus as set forth in claim 6 characterized in that the function generator (38) forms a linearization member (43) which receives the parameter (35, 35') or the differentiation value (42) as an input signal and at its output there can be taken off a control signal (44) which is in a linear relationship with the spacing or the change in the spacing between the two contact regions (29, 29') .

8. An actuating apparatus as set forth in claim 6 characterized in that the function generator (38) has a first threshold stage (47) which receives the parameter (35, 35') as an input signal and at whose output a control signal (44') can be taken off, which is of a first characteristic value when the parameter (35, 35') is greater than or equal to a predetermined parameter threshold value (49) and which is of a second characteristic value when the parameter (35, 35') is less than the predetermined parameter threshold value (49).

9. An actuating apparatus as set forth in claim 6 characterized in that the function generator (38) has a second threshold stage (50) which receives the differentiation value (42) as an input signal and at whose output a control signal (44'') can be taken off, which is of a constant first differentiation magnitude when the differentiation value (42) is greater than or equal to a predetermined differentiation value threshold (51) and which is of a second differentiation magnitude when the differentiation value (42) is less than the predetermined differentiation value threshold (51).

10. An actuating apparatus as set forth in claim 6 characterized in that the function generator (38) has a table memory (53) in which there is associated with each digital value of the parameter (35') and/or of the differentiation value (42) a corresponding value of the control signal (44).

11. An actuating apparatus as set forth in claim 14 characterized in that the elastic material is porous.

12. An actuating apparatus as set forth in claim 1 characterized in that the shaped body (61) is in the form of a compressibly shock-

absorbing foot well lining which reduces its electrical resistance upon a compression in respect of volume.

13. An actuating apparatus as set forth in claim 12 characterized in that the shaped body (61) comprises a cellular polyurethane or a cellular vulkollan.

14. An actuating apparatus as set forth in claim 1 characterized in that the shaped body has inclusions, in particular in the form of electrically conductive balls or hollow balls (70) which in particular are also compressible.

15. An actuating apparatus as set forth in one of claims 1, 20, 21 and 22 characterized in that the shaped body (61) has a compression characteristic (80) $E = f(S)$ with regions of different compression in respect of volume, in particular with a region (81) with a low level of compression in respect of volume and a region (82) of high compression in respect of volume, in such a way that a substantially linear relationship between the compression stroke distance S and the mechanical energy E absorbed upon compression exists in the region of the low level of compression in respect of volume and an over-proportionally non-linear relationship between the compression stroke distance S and the mechanical energy E absorbed upon compression exists in the region of the high level of compression in respect of volume.

16. An actuating apparatus as set forth in claim 15 characterized in that the compression characteristic (80) is of a substantially quadratic or exponential configuration in the region (82) of the high level of compression in respect of volume.

17. An actuating apparatus as set forth in claim 1 characterized in that the signal converter (26) is enclosed by an insulating material which is stiff in the region or regions (31, 31') of the first and/or second contact region (29, 29') so that a pressure exerted locally in the stiffened region is applied to the shaped body distributed uniformly over the stiffened region (31, 31'), and is yielding in the other regions.

18. An actuating apparatus as set forth in claim 1 characterized in that in a region (26) which is towards the person actuating the apparatus, the surface of the signal converter is provided with an increased coefficient of friction or a recess which is matched to the sole of the person operating the apparatus, so that same has a hold which is secured to prevent lateral displacement thereof.

19. An actuating apparatus as set forth in claim 1 characterized in that the shaped body comprises at least two shaped body portions (27, 28) which are arranged in conductive mutually superposed relationship in a direction perpendicular to a connecting line between the first contact region (29) and the second contact region (29'), wherein the moduli of elasticity of the materials of the shaped body portions (27, 28) are of different magnitudes, and the shaped body portions (27, 28) are of different extents along the connecting line so that there occurs a spacing of the two contact regions (29, 29'), which is referred to as the pressure point and at which only one of the two shaped body portions (27, 28) is substantially completely compressed.

20. An actuating apparatus as set forth in claim 1 characterized in that there are provided means which detect the derivative of the variation in the electrical resistance and which increase the acceleration of the motor vehicle upon a relatively fast change in the electrical resistance so that a kick-down effect can be produced.

21. An actuating apparatus as set forth in claim 1 characterized in that it is part of a group of a plurality of actuating apparatuses (21, 22, 23) which are integrated into an overall shaped body (24), wherein the actuating surfaces (25) of the three actuating apparatuses (21, 22, 23) are disposed in mutually juxtaposed relationship operably in a surface of the overall shaped body (24) in such a way that the actuating surface (25) of the first actuating apparatus (21) is arranged to the right, the actuating surface of the second actuating apparatus (22) is arranged at the center and the actuating surface of the third actuating apparatus (23) is arranged to the left.

22. An actuating apparatus as set forth in claim 21 characterized in that the actuating group is incorporated in a wall which separates the passenger compartment from the engine compartment, wherein the three actuating surfaces (25) face towards the driver.

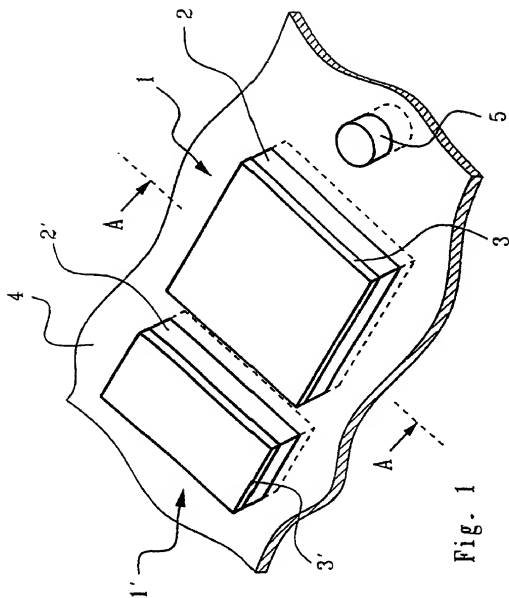
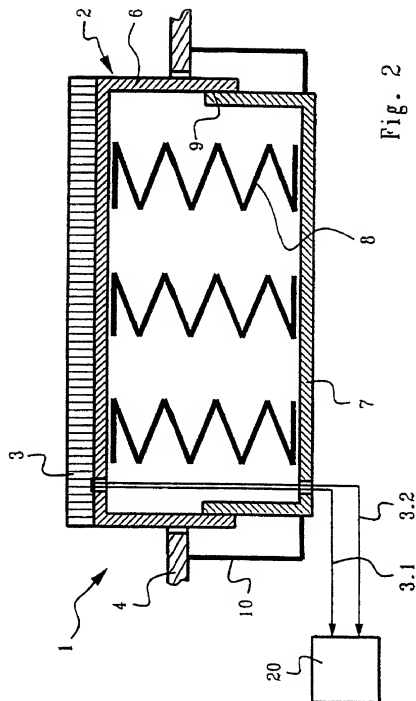


Fig. 1



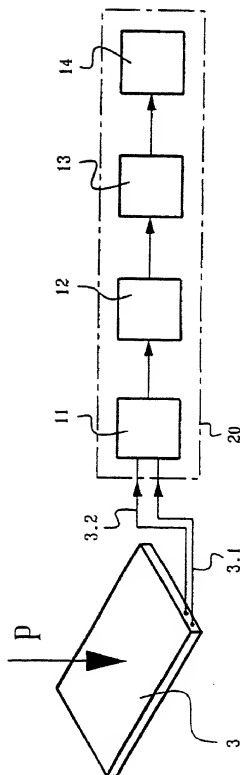


Fig. 3

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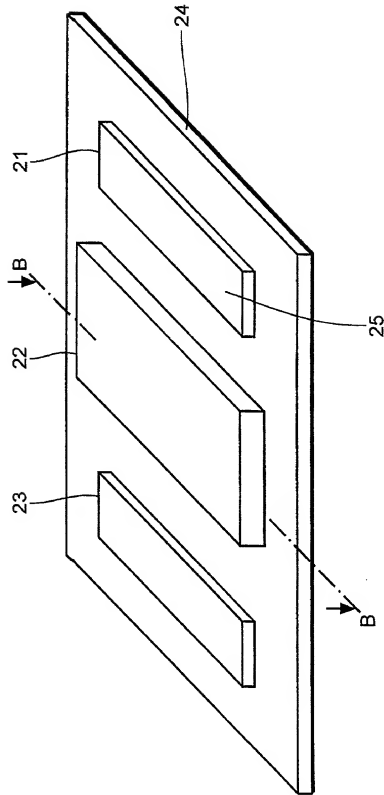


Fig. 4

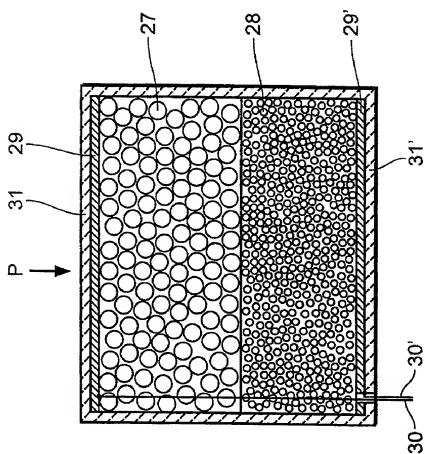


Fig.5



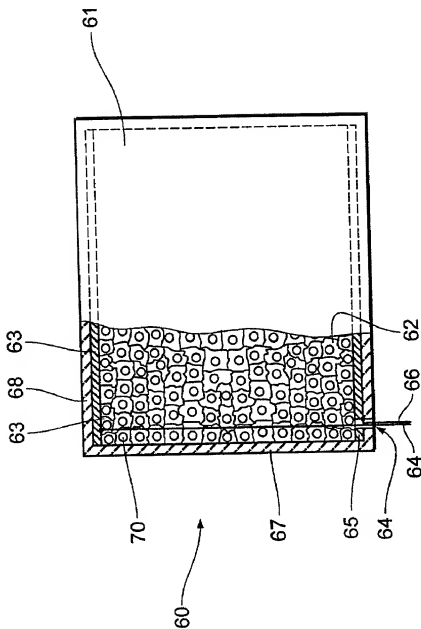


Fig. 7

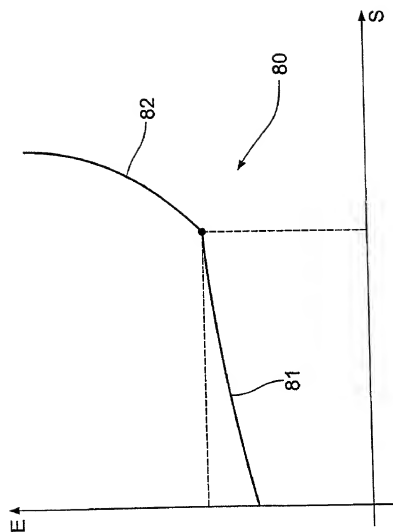


Fig. 8

DECLARATION AND POWER OF ATTORNEY
FOR PATENT APPLICATIONS

PATENT

Docket No.: 40265/DBP/E43

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled MOTOR VEHICLE ACTUATING DEVICE, the specification of which is attached hereto unless the following is checked:

X was filed on March 11, 1999 as United States Application Number or PCT International Application Number PCT/EP99/01585 and was amended on _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR § 1.56.

I hereby claim foreign priority benefits under 35 U.S.C. § 119(a)-(d) or § 365(b) of the foreign application(s) for patent or inventor's certificate, or § 365(a) of any PCT International application which designated at least one country other than the United States, listed below and have also identified below, any foreign application for patent or inventor's certificate, or PCT International application having a filing date before that of the application on which priority is claimed.

Prior Foreign Application(s)

<u>Application Number</u>	<u>Country</u>	<u>Filing Date (day/month/year)</u>	<u>Priority Claimed</u>
198 11 268.8	Germany	11 March 1998	YES

I hereby claim the benefit under 35 U.S.C. § 119(e) of any United States provisional application(s) listed below.

<u>Application Number</u>	<u>Filing Date</u>
---------------------------	--------------------

I hereby claim the benefit under 35 U.S.C. § 120 of any United States application(s), or any PCT International application designating the United States, listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States or PCT International application in the manner provided by the first paragraph of 35 U.S.C. § 112, I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR § 1.56 which became available between the filing date of the prior application and the national or PCT International filing date of this application:

<u>Application Number</u>	<u>Filing Date</u>	<u>Patented/Pending/Abandoned</u>
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POWER OF ATTORNEY: I hereby appoint the following attorneys and agents of the law firm CHRISTIE, PARKER & HALE, LLP to prosecute this application and any international application under the Patent Cooperation Treaty based on it and to transact all business in the U.S. Patent and Trademark Office connected with either of them in accordance with instructions from the assignee of the entire interest in this application;

**DECLARATION AND POWER OF ATTORNEY
FOR PATENT APPLICATIONS**

Docket No. 40265/DBP/E43

or from the first or sole inventor named below in the event the application is not assigned; or from Eisenfuhr, Speiser & Partner, in the event the power granted herein is for an application filed on behalf of a foreign attorney or agent.

R. W. Johnston	(17,968)	Grant T. Langton	(39,739)	Jun-Young E. Jeon	(43,693)
D. Bruce Prout	(20,958)	Constantine Marantidis	(39,759)	Marc A. Karish	(44,816)
Hayden A. Carney	(22,653)	Daniel R. Kimbell	(34,849)	John F. O'Rourke	(38,985)
Richard J. Ward, Jr.	(24,187)	Craig A. Gelfound	(41,032)	Richard J. Paciulan	(28,248)
Russell R. Palmer, Jr.	(22,994)	Syed A. Hasan	(41,057)	Josephine E. Chang	(46,083)
LeRoy T. Rahn	(20,356)	Kathleen M. Olster	(42,052)	Frank L. Cire	(42,419)
Richard D. Seibel	(22,134)	Daniel M. Cavanagh	(41,661)	Harold E. Wurst	(22,183)
Walter G. Maxwell	(25,355)	Molly A. Holman	(40,022)	Robert A. Green	(28,301)
William P. Christie	(29,371)	Lucinda G. Auciello	(42,270)	Derrick W. Reed	(40,138)
David A. Dillard	(30,831)	Norman E. Carte	(30,455)	John W. Peck	(44,284)
Thomas J. Daly	(32,213)	Joel A. Kauth	(41,886)	Stephen D. Burbach	(40,235)
Vincent G. Gioia	(19,959)	Patrick Y. Ikehara	(42,681)	David B. Sandelands, Jr.	(46,023)
Edward R. Schwartz	(31,135)	Mark Garscia	(31,953)	Heidi L. Eisenhut	(P-46,812)
John D. Carpenter	(34,133)	Gary J. Nelson	(44,257)	Nicholas J. Pauley	(44,999)
David A. Plumley	(37,208)	Raymond R. Tabandeh	(43,945)	Mark J. Marcelli	(36,593)
Wesley W. Monroe	(39,778)	Phuong-Quan Hoang	(41,839)		
Gregory S. Lampert	(35,581)	Cynthia A. Bonner	(44,548)		

The authority under this Power of Attorney of each person named above shall automatically terminate and be revoked upon such person ceasing to be a member or associate of or of counsel to that law firm.

DIRECT TELEPHONE CALLS TO : D. Bruce Prout, 626/795-9900
SEND CORRESPONDENCE TO : CHRISTIE, PARKER & HALE, LLP
P.O. Box 7068, Pasadena, CA 91109-7068

I declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Full name of sole or first joint inventor Helke Lob	Inventor's signature <i>Helke Lob</i>	Date 4, October, 2000
Residence and Post Office Address Ehrwalder Stasse 82, D-81377 Munich, Germany	Citizenship Germany	